

Expand All | Collapse All

[Home](#)[Faculty](#)[Projects](#)[Labs](#)[Videos](#)[News](#)[Robotics Seminar series](#)[Directions/maps for visitors](#)[Contact us](#)[Institute for Systems Research](#)[Clark School](#)

search

 Robotics  UMD[Search robotics news archives](#)

SHARE



## ■ New NSF grant funds research to build network of tiny robots for bridge inspection



Associate Professor **Nuno Martins** (ECE/ISR) is the principal investigator of a new National Science Foundation Cyber-Physical Systems Collaborative Research grant, **?Designing semi-autonomous networks of miniature robots for inspection of bridges and other large infrastructures.?**

Associate Professor **Sarah Bergbreiter** (ME/ISR) and Associate Professor **Richard La** (ECE/ISR) join him as co-PIs.

The three-year, \$850K grant is part of NSF's National Robotics Initiative.

U.S. Department of Transportation figures indicate the country has 605,102 bridges. Approximately 64 percent are more than 30 years old and 11 percent are structurally deficient. Currently, visual inspection is the standard procedure used to identify structural flaws, determine precautionary measures, specify repairs and safeguard the public. Each inspection requires on-site evaluation by experts who spend many hours assessing the integrity of the structure.

This new research will create a self-organizing network of small robots that could aid in visually inspecting bridges and other large civilian infrastructure. As they create the network, the researchers will establish new design and performance analysis principles and technologies.

The networked robots could remotely and routinely inspect complicated structures, like the assemblage of girders supporting a suspension bridge. The robots will use wireless information exchange to autonomously coordinate and cooperate in the inspection, and whenever possible, they will report back images and key measurements to experts for evaluation. The tiny networked robots will be able to access tight spaces, operate under various weather conditions, and autonomously execute tasks for long periods of time.

Because experts can remotely supervise the robot network, both cost and the time between the on-site inspections they need to make will be reduced. At the same time, the flexible system will increase the regularity of inspections, improving the detection and diagnosis of problems. The goal is to increase safety and support effective preventive maintenance.

The researchers are collaborating with **Resensys**, a company that specializes in remote bridge monitoring. Resensys is a portfolio company of the Maryland Technology Enterprise Institute's (Mtech) **Technology Advancement Program**, an Mtech **VentureAccelerator** graduate and a former UMD **\$75K Business Plan Competition** winner. Resensys' President and CTO **Mehdi Kalantari** (EE Ph.D. 2005) is an assistant research scientist in the Electrical

### Current Headlines

**Alum Dimitris Tsakiris improves propulsion of robotic octopus**

**Alum Xiaobo Tan developing robotic fish to 'stalk' real fish in the Great Lakes**

**UMD engineers create tiny, robust rubber micro-component.**

**Virtual Demonstrations and Crowdsourcing Could Lead Advancements in Autonomous Robots**

**Brain-behavior initiative workshop draws 160 faculty, deans, administrators for wide-ranging discussions**

**UMD Clark School to Host Mpack Week: Disaster Resilience**

**Mpack Week to feature robotics for disaster response**

**New NSF grant funds research to build network of tiny robots for bridge inspection**

**University of Maryland Orbital Debris Education and Research Center to Host Inaugural Workshop**

**Students present final projects for 2014 NSF Microrobotics REU**

New NSF grant funds research to build network of tiny robots for bridge inspection and Computer Engineering Department.

The system will be tested in collaboration with the Maryland State Highway Administration, which will provide feedback and expertise throughout the project.

**Related Articles:**

- [\*\*Students present final projects for 2014 NSF Microrobotics REU\*\*](#)
- [\*\*Bergbreiter to attend NAE U.S. Frontiers of Engineering Symposium\*\*](#)
- [\*\*Bergbreiter wins Clark School MRI award\*\*](#)
- [\*\*Sarah Bergbreiter wins PECASE Award\*\*](#)
- [\*\*Bergbreiter one of '25 women in robotics you need to know about'\*\*](#)
- [\*\*ECE Students Take Top Prize at Michigan Hackathon for Intelligent Trashcan\*\*](#)
- [\*\*UAE students, Northrop Grumman engineers tour robotics laboratories\*\*](#)
- [\*\*REU in Miniature Robotics holds final project symposium\*\*](#)
- [\*\*Alum Serban Sabau joins Stevens Institute as assistant professor\*\*](#)
- [\*\*IEEE Spectrum website features quadruped microrobot\*\*](#)

August 29, 2014

[\*\*«Previous Story\*\*](#)

[\*\*Next Story»\*\*](#)

[\*\*▲ Back to top\*\*](#)

[UMD Home](#) | [Clark School Home](#) | [ISR Home](#) | [About Us](#)

**University of Maryland, Copyright 2013**